ASSIGNMENT 6

#include <WiFi.h>

#include <PubSubClient.h>

int echopin=4;

int trigpin=5;

int LIGHT\_INTENISTY;

int ultrasonic;

String command;

String data="";

void callback(char\* topic, byte\* payload, unsigned int payloadLength);

// CHANGE TO YOUR WIFI CREDENTIALS

const char\* ssid = "Redmi";//your wifi ssid

const char\* password = "12345671";//your password

// CHANGE TO YOUR DEVICE CREDENTIALS AS PER IN IBM BLUMIX

#define ORG "lz5frl"

#define DEVICE\_TYPE "ESP32"

#define DEVICE\_ID "63041"

#define TOKEN "12345678" // Authentication Token OF THE DEVICE

// PIN DECLARATIONS

#define led1 2

#define led2 0

//-------- Customise the above values --------

const char publishTopic[] = "iot-2/evt/Data/fmt/json";

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";

char topic[] = "iot-2/cmd/home/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING

char authMethod[] = "use-token-auth";

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID;

WiFiClient wifiClient;

PubSubClient client(server, 1883, callback, wifiClient);

int publishInterval = 5000; // 30 seconds

long lastPublishMillis;

void publishData();

void setup() {

Serial.begin(115200);

Serial.println();

pinMode(echopin,INPUT);

pinMode(trigpin,OUTPUT);

wifiConnect();

mqttConnect();

}

void loop() {

if (millis() - lastPublishMillis > publishInterval)

{

publishData();

lastPublishMillis = millis();

}

if (!client.loop()) {

mqttConnect();

}

}

void wifiConnect() {

Serial.print("Connecting to "); Serial.print(ssid);

WiFi.begin(ssid, password);

while (WiFi.status() != WL\_CONNECTED) {

delay(500);

Serial.print(".");

}

Serial.print("WiFi connected, IP address: ");

Serial.println(WiFi.localIP());

}

void mqttConnect() {

if (!client.connected())

{

Serial.print("Reconnecting MQTT client to "); Serial.println(server);

while (!client.connect(clientId, authMethod, token)) {

Serial.print(".");

delay(500);

}

initManagedDevice();

Serial.println();

}

}

void initManagedDevice() {

if (client.subscribe(topic)) {

Serial.println("subscribe to cmd OK");

} else {

Serial.println("subscribe to cmd FAILED");

}

}

void callback(char\* topic, byte\* payload, unsigned int payloadLength) {

Serial.print("callback invoked for topic: ");

Serial.println(topic);

for (int i = 0; i < payloadLength; i++) {

command+= (char)payload[i];

}

Serial.print("data: "+ command);

control\_func();

command= "";

}

void control\_func()

{

if(command== "lightoff")

{

digitalWrite(led1,LOW);

digitalWrite(led2,LOW);

Serial.println(".......lights are off..........");

}

else if(command== "lighton")

{

digitalWrite(led1,HIGH);

digitalWrite(led2,HIGH);

Serial.println(".......lights are on..........");

}

else

{

Serial.println("......no commands have been subscribed..........");

}

}

void publishData()

{

digitalWrite(trigpin,HIGH);

delay(1000);

digitalWrite(trigpin,LOW);

int a=analogRead(15);

Serial.println("the ldr value is");

Serial.println(a);

int duration=pulseIn(echopin,HIGH);

int distance=duration\*0.0343/2;

Serial.println("the distance is");

Serial.println(distance);

delay(2000);

String payload = "{\"d\":{\"ultrasonic\":";

payload +=distance ;

payload += ",""\"LIGHT\_INTENSITY\":";

payload += a;

payload += "}}";

Serial.print("\n");

Serial.print("Sending payload: "); Serial.println(payload);

if (client.publish(publishTopic, (char\*) payload.c\_str())) {

Serial.println("Publish OK");

} else {

Serial.println("Publish FAILED");

}

}